

Amendments to the Claims

This listing of claims will replace all prior versions, and listings, of claims in the application.

1. (Currently Amended) A sound wave-based tracking system comprising:

a speaker at a fixed location for automatically transmitting a given signal combined with one or more other signals, wherein said given signal has a given frequency above an audible range and said other signals have frequencies in the audible range;

a plurality of microphones mounted upon an object for receiving said given signal; and
a computing device for determining at least one of a position and an orientation of said object from a delay of said given signal received by each of said plurality of microphones,
wherein said signal comprises a marker and wherein said delay is determined as a function of a delay of said marker received by each of said plurality of microphones relative to said marker of a reference signal.

2-5. (Canceled).

6. (Previously Presented) The sound wave-based tracking system according to Claim 1, wherein said plurality of microphones communicate wirelessly with said computing device.

7. (Previously Presented) A method of tracking comprising:
transmitting simultaneously a first non-audible signal from a first speaker and a second non-audible signal from a second speaker;
receiving said first and second non-audible signals at a plurality of microphones;
determining a delay for each of said received first and second non-audible signals for each of said plurality of microphones; and
determining at least one of a relative position and a relative orientation of said plurality of microphones as a function of said determined delays.

8-10. (Canceled).

11. (Previously Presented) The method of tracking according to Claim 7, wherein:
said first non-audible signal comprises a sine wave having a first frequency; and
said second non-audible signal comprises a sine wave having a second frequency.

12. (Previously Presented) The method of tracking according to Claim 7, further comprising controlling a cursor of a computing device as a function of said determined at least one of said relative position and said relative orientation.

13. (Previously Presented) The method of tracking according to Claim 7, further comprising controlling an application executing on a computing device as a function of said determined at least one of said relative position and said relative orientation.

14. (Previously Presented) A computing system comprising:

a plurality of speakers for transmitting one or more sound waves in the audible range, and wherein a first speaker automatically transmits a first signal at a first frequency above the audible range and a second speaker automatically transmits a second signal at a second frequency above the audible range substantially simultaneously with the first signal;

a plurality of microphones mounted on an assembly for receiving said first and second signals; and

a computing device coupled to control said speakers and coupled to receive said first and second signals from each of said plurality of microphones, said computing device for determining at least one of a relative position and a relative orientation of said assembly based on delay differences of said first and second signals received from each of said plurality of microphones.

15. (Original) The computing system as described in Claim 14, wherein said computing device is a personal computer and wherein said personal computer is wirelessly coupled to said plurality of microphones.

16. (Original) The computing system as described in Claim 14, wherein said computing device is a game console and wherein said game console is wirelessly coupled to said plurality of microphones.

17. (Original) The computing system as described in Claim 14, wherein said plurality of microphones comprise two microphones and wherein said determined at least one of said relative position and said relative orientation is within a single spatial plane.

18. (Original) The computing system as described in Claim 14, wherein said plurality of microphones comprise three microphones and wherein said determined at least one of said relative position and said relative orientation is within two spatial planes.

19. (Original) The computing system as described in Claim 14, wherein said computing device comprises a display screen and wherein said computing device translates said determined at least one of said relative position and said relative orientation into a cursor position on said display screen.

20. (Previously Presented) The computing system as described in Claim 14, wherein said sound wave is a sine wave.

21-22. (Canceled).

23. (New) A sound wave-based tracking system comprising:

a speaker at a fixed location for automatically transmitting a given signal combined with one or more other signals, wherein said given signal has a given frequency above an audible range and said other signals have frequencies in the audible range;

a plurality of microphones mounted upon an object for receiving said given signal; and

a computing device for determining at least one of a position and an orientation of said object from a delay of said given signal received by each of said plurality of microphones, wherein said delay is determined as a function of a time delay of said signal received by each of said plurality of microphones relative to a reference signal.

24. (New) The sound wave-based tracking system according to Claim 23, wherein said sound wave is a sine wave.

25. (New) The sound wave-based tracking system according to Claim 23, wherein said computing device comprises a display screen and wherein said computing device translates said determined at least one of said relative position and said relative orientation into a cursor position on said display screen.

26. (New) The sound wave-based tracking system according to Claim 23, wherein said plurality of microphones communicate wirelessly with said computing device.

27. (New) The sound wave-based tracking system according to Claim 1, wherein said plurality of microphones comprise two microphones and wherein said determined at least one of said position and said orientation is within a single spatial plane.

28. (New) The sound wave-based tracking system according to Claim 1, wherein said plurality of microphones comprise three microphones and wherein said determined at least one of said position and said orientation is within two spatial planes.